

Prentice Hall Open Source Software Development Series

Using BusyBox

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SECTION 11.2

BusyBox Configuration

Notice that the BusyBox utility, as compiled using the default configuration, requires the three shared libraries in Listing 11-2. Had we elected to build BusyBox as a static binary, 1dd would simply issue a message telling us that the BusyBox binary is not a dynamic executable. In other words, it requires no shared libraries to resolve any unresolved dependencies in the executable. Static linking yields a smaller footprint on a root file system because no shared libraries are required. However, building an embedded application without shared libraries means that you have none of the familiar C library functions available to your applications.

We cover the other options from Listing 11-1 in the next section.

11.2.1 Cross-Compiling BusyBox

As mentioned at the beginning of the chapter, the authors of BusyBox intended the package to be used in a cross-development environment, so building BusyBox in such an environment is quite easy. In most cases, the only requirement is to specify the prefix to the cross-compiler on your development workstation. This is specified in Build Options in the BusyBox configuration utility by selecting the option to build BusyBox with a cross-compiler. You then are presented with an option to enter the cross-compiler prefix. The prefix you enter depends on your cross-development environment. Some examples include xscale_be- or ppc-linux-. We cover this in more detail in the next chapter when we examine the embedded development environment.

The final option in Listing 11-1 is for any extra flags you might want to include on the compiler command line. These might include options for generating debug information (-g), options for setting the optimization level (-02, for example), and other compiler options that might be unique to your particular installation and target system.

BusyBox Operation

11.3 BusyBox Operation

When you build BusyBox, you end up with a binary called, you guessed it, busyBox. BusyBox can be invoked from the binary name itself, but it is more usually launched via a *symlink*. When BusyBox is invoked without command-line parameters, it produces a list of the functions that were enabled via the configuration. Listing 11-3 shows such an output (it has been formatted slightly to fit the page width).

LISTING 11-3 BusyBox Usage

```
root@coyote # ./busybox
BusyBox v1.01 (2005.12.03-18:00+0000) multi-call binary

Usage: busybox [function] [arguments]...
   or: [function] [arguments]...

BusyBox is a multi-call binary that combines many common Unix utilities into a single executable. Most people will create a link to busybox for each function they wish to use and BusyBox will act like whatever it was invoked as!

Currently defined functions:
[, ash, basename, bunzip2, busybox, bzcat, cat, chgrp, chmod, chown, chroot, chvt, clear, cmp, cp, cut, date, dd, deallocvt, df, dirname, dmesg, du, echo, egrep, env, expr, false, fgrep, find, free, grep, gunzip, gzip, halt, head, hexdump, hostname,
```

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id, ifconfig, init, install, kill, killall, klogd, linuxrc, ln, logger, ls, mkdir, mknod, mktemp, more, mount, mv, openvt, pidof, ping, pivot_root, poweroff, ps, pwd, readlink, reboot, reset, rm, rmdir, route, sed, sh, sleep, sort, strings, swapoff, swapon, sync, syslogd, tail, tar, tee, test, time, touch, tr, true, tty, umount, uname, uniq, unzip, uptime, usleep, vi, wc, wget, which, whoami, xargs, yes, zcat

From Listing 11-3, you can see the list of functions that are enabled in this BusyBox build. They are listed in alphabetical order from ash (a shell optimized for small memory footprint) to zcat, a utility used to decompress the contents of a compressed file. This is the default set of utilities enabled in this particular BusyBox snapshot.

To invoke a particular function, execute busybox with one of the defined functions passed on the command line. Thus, to display a listing of files in the current directory, execute this command:

[root@coyote]# ./busybox ls

Another important message from the BusyBox usage message in Listing 11-3 is the short description of the program. It describes BusyBox as a multicall binary, combining many common utilities into a single executable. This is the purpose of the symlinks mentioned earlier. BusyBox was intended to be invoked by a symlink named for the function it will perform. This removes the burden of having to type a two-word command to invoke a given function, and it presents the user with a set of familiar commands for the similarly named utilities. Listings 11-4 and 11-5 should make this clear.